



MATHEMATICS: SPECIALIST

UNITS 3C AND 3D

FORMULA SHEET 2014

Copyright

© School Curriculum and Standards Authority, 2014

This document—apart from any third party copyright material contained in it—may be freely copied, or communicated on an intranet, for non-commercial purposes by educational institutions, provided that it is not changed in any way and that the School Curriculum and Standards Authority is acknowledged as the copyright owner.

Copying or communication for any other purpose can be done only within the terms of the Copyright Act or by permission of the Authority

Copying or communication of any third party copyright material contained in this document can be done only within the terms of the Copyright Act or by permission of the copyright owners.

This document is valid for teaching and examining until 31 December 2014.

index	
Vectors	3
Trigonometry	3
Functions	4
	_
Matrices	5
Complex numbers	6
Exponentials and logarithms	7
Mathematical reasoning	7
Measurement	8

Vectors

Magnitude: $|(a_1, a_2, a_3)| = \sqrt{a_1^2 + a_2^2 + a_3^2}$

Dot product: $\mathbf{a} \cdot \mathbf{b} = |\mathbf{a}| |\mathbf{b}| \cos \theta = a_1 b_1 + a_2 b_2 + a_3 b_3$

Triangle inequality: $|\mathbf{a} + \mathbf{b}| \le |\mathbf{a}| + |\mathbf{b}|$

Vector equation of a line in space: one point and the slope: $\mathbf{r} = \mathbf{a} + \lambda \mathbf{b}$

two points A and B: $\mathbf{r} = \mathbf{a} + \lambda(\mathbf{b} - \mathbf{a})$

Cartesian equations of a line in space: $\frac{x-a_1}{b_1} = \frac{y-a_2}{b_2} = \frac{z-a_3}{b_3}$

Parametric form of vector equation of a line in space:

 $x = a_1 + \lambda b_1 \dots (1)$

 $y = a_2 + \lambda b_2$(2)

 $z = a_3 + \lambda b_3 \dots (3)$

Vector equation of a plane in space: $\mathbf{r} \cdot \mathbf{n} = c$ or $\mathbf{r} = \mathbf{a} + \lambda \mathbf{b} + \mu \mathbf{c}$

Trigonometry

In any triangle ABC: $\frac{a}{\sin A} = \frac{b}{\sin B} = \frac{c}{\sin C}$ $a^2 = b^2 + c^2 - 2bc \cos A$ $\cos A = \frac{b^2 + c^2 - a^2}{2bc}$ $A = \frac{1}{2}ab \sin C$

In a circle of radius r, for an arc subtending angle θ (radians) at the centre:

Length of arc $= r\theta$

Area of segment $=\frac{1}{2} r^2 (\theta - \sin \theta)$ Area of sector $=\frac{1}{2} r^2 \theta$

Identities: $\cos^2 \theta + \sin^2 \theta = 1$ $\cos 2\theta = \cos^2 \theta - \sin^2 \theta$

 $\cos(\theta \pm \varphi) = \cos\theta \cos\varphi \mp \sin\theta \sin\varphi \qquad = 2\cos^2\theta - 1$

 $=1-2\sin^2\theta$

 $\sin (\theta \pm \varphi) = \sin \theta \cos \varphi \pm \cos \theta \sin \varphi$ $\sin 2\theta = 2\sin \theta \cos \theta$

 $\tan(\theta \pm \varphi) = \frac{\tan\theta \pm \tan\varphi}{1 \mp \tan\theta \tan\varphi} \qquad \tan 2\theta = \frac{2\tan\theta}{1 - \tan^2\theta}$

 $\lim_{x \to 0} \frac{\sin x}{x} = 1$ $\lim_{x \to 0} \frac{1 - \cos x}{x} = 0$

Simple Harmonic Motion: If $\frac{d^2x}{dt^2} = -k^2x$ then $x = A\sin(kt + \alpha)$ or $x = A\cos(kt + \beta)$ and

 $v^2 = k^2 (A^2 - x^2)$, where A is the amplitude of the motion, α and β are phase angles, v is the velocity and x is the displacement.

Functions

If f(x) = y then $f'(x) = \frac{dy}{dx}$ Differentiation:

If $f(x) = x^n$ then $f'(x) = nx^{n-1}$

If $f(x) = e^x$ then $f'(x) = e^x$

If $f(x) = \ln x$ then $f'(x) = \frac{1}{x}$

If $f(x) = \sin x$ then $f'(x) = \cos x$

If $f(x) = \cos x$ then $f'(x) = -\sin x$

If $f(x) = \tan x$ then $f'(x) = \sec^2 x = \frac{1}{\cos^2 x}$

If y = f(x) g(x)Product rule:

If y = uv

then y' = f'(x) g(x) + f(x) g'(x)

then $\frac{dy}{dx} = \frac{du}{dx}v + u\frac{dv}{dx}$

Quotient rule:

If $y = \frac{f(x)}{g(x)}$

or

or If $y = \frac{u}{v}$ then $\frac{dy}{dx} = \frac{\frac{du}{dx}v - u}{v^2}\frac{\frac{dv}{dx}}{v}$

then $y' = \frac{f'(x) g(x) - f(x) g'(x)}{(g(x))^2}$

Incremental formula: $\delta y \simeq \frac{dy}{dx} \delta x$

or

or $f(x+h)-f(x) \simeq f'(x)h$

Chain rule:

If y = f(g(x))

then y' = f'(g(x)) g'(x)

If y = f(u) and u = g(x)

then $\frac{dy}{dx} = \frac{dy}{du} \times \frac{du}{dx}$

Integration:

Powers:

 $\int x^n dx = \frac{x^{n+1}}{n+1} + c, \ n \neq -1$

Exponentials:

 $\int e^x dx = e^x + c$

Logarithms: $\int_{x}^{1} dx = \ln|x| + c$

 $\int \sin x \, dx = -\cos x + c$ Trigonometric:

 $\int \cos x \, dx = \sin x + c$

 $\int \frac{1}{\cos^2 x} \ dx = \tan x + c$

Fundamental Theorem of Calculus:

 $\frac{d}{dx}\int_a^x f(t)dt = f(x)$ and $\int_a^b f'(x)dx = f(b) - f(a)$

Functions

Quadratic function:

If
$$y = ax^2 + bx + c$$
 and $y = 0$, then $x = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$ for $x \in \mathbb{C}$

Piecewise-defined functions:

Absolute value function: $|x| = \begin{cases} x, & \text{for } x \ge 0 \\ -x, & \text{for } x < 0 \end{cases}$

Sign function: $\operatorname{sgn}(x) = \begin{cases} 1, & \text{for } x > 0 \\ 0, & \text{for } x = 0 \\ -1, & \text{for } x < 0 \end{cases}$

Greatest integer function: int (x) = greatest integer $\le x$ for all x

Matrices

If
$$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$$
 then $|A| = \det A = ad - bc$
$$A^{-1} = \frac{1}{(ad - bc)} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$$

Dilation =
$$\begin{bmatrix} a & 0 \\ 0 & a \end{bmatrix}$$
 Shear =
$$\begin{bmatrix} 1 & a \\ 0 & 1 \end{bmatrix}$$
 or
$$\begin{bmatrix} 1 & 0 \\ a & 1 \end{bmatrix}$$

$$\mathsf{Rotation} = \begin{bmatrix} \cos\theta & -\sin\theta \\ \sin\theta & \cos\theta \end{bmatrix} \qquad \qquad \mathsf{Reflection} = \begin{bmatrix} \cos 2\theta & \sin 2\theta \\ \sin 2\theta & -\cos 2\theta \end{bmatrix}$$

Complex numbers

For z = a + ib, where $i^2 = -1$

Argument: $\arg z = \theta$, where $\tan \theta = \frac{b}{a}$ and $-\pi < \theta \le \pi$

Modulus: $\mod z = |z| = |a + ib| = \sqrt{a^2 + b^2} = r$

Product: $|z_1 z_2| = |z_1| |z_2|$ $\arg(z_1 z_2) = \arg z_1 + \arg z_2$

Polar form:

For $z = r \operatorname{cis} \theta$, where r = |z| and $\theta = \arg z$:

 $cis(\theta + \varphi) = cis \theta cis \varphi$ $cis(\theta + \varphi) = cis \theta cis \varphi$ $cis(\theta + \varphi) = cis \theta cis \varphi$ $cis(\theta + \varphi)$ cis(0) = 1 $z_1 z_2 = r_1 r_2 cis(\theta + \varphi)$ $\frac{z_1}{z_2} = \frac{r_1}{r_2} cis(\theta - \varphi)$

Exponential form:

 $z = re^{i\theta}$, where r = |z| and $\theta = \arg z$

For complex conjugates:

z = a + bi $z = r \operatorname{cis} \theta$ $z = re^{i\theta}$ $z = z = |z|^{2}$ $\overline{z} = |z|^{2}$

Exponentials and logarithms

For a, b > 0 and m, n real:

$$a^{m}a^{n} = a^{m+n}$$

$$a^{0} = 1$$

$$a^{-n} = \frac{1}{a^{n}}$$

$$(ab)^{m} = a^{m}b^{m}$$

For m an integer and n a positive integer:

$$a^{\frac{1}{n}} = \sqrt[n]{a^m} = \sqrt[n]{a^m} = \left(\sqrt[n]{a}\right)^m$$

For a, b, y, m and n positive real and k real:

$$1 = a^{0} \Leftrightarrow \log_{a} 1 = 0$$

$$y = a^{x} \Leftrightarrow \log_{a} y = x$$

$$\log_{a} mn = \log_{a} m + \log_{a} n$$

$$a = a^{1} \Leftrightarrow \log_{a} a = 1$$

$$\log_{a} m = \frac{\log_{b} m}{\log_{b} a} \text{ (change of base)}$$

$$\log_{a} (m^{k}) = k \log_{a} m$$

If
$$\frac{dP}{dt} = kP$$
, then $P = P_0 e^{kt}$

Mathematical reasoning

De Moivre's theorem:

$$(\operatorname{cis} \theta)^{n} = (\operatorname{cos} \theta + i \operatorname{sin} \theta)^{n}$$

$$(\operatorname{cis} \theta)^{n} = \operatorname{cos} n\theta + i \operatorname{sin} n\theta$$

$$z^{n} = |z|^{n} \operatorname{cis} (n\theta)$$

$$z^{\frac{1}{q}} = |z|^{\frac{1}{q}} \left[\operatorname{cos} \left(\frac{\theta + 2\pi k}{q} \right) + i \operatorname{sin} \left(\frac{\theta + 2\pi k}{q} \right) \right]$$
 for k an integer.

Measurement

Circle: $C = 2\pi r = \pi D$, where C is the circumference,

r is the radius and D is the diameter

 $A = \pi r^2$, where A is the area

Triangle: $A = \frac{1}{2}bh$, where b is the base and h is the perpendicular height

Parallelogram: A = bh

Trapezium: $A = \frac{1}{2}(a+b)h$, where a and b are the lengths of the parallel sides

Prism: V = Ah, where V is the volume and A is the area of the base

Pyramid: $V = \frac{1}{3} Ah$

Cylinder: $S = 2\pi rh + 2\pi r^2$, where S is the total surface area

 $V = \pi r^2 h$

Cone: $S = \pi rs + \pi r^2$, where *s* is the slant height

 $V = \frac{1}{3}\pi r^2 h$

Sphere: $S = 4\pi r^2$

 $V = \frac{4}{3} \pi r^3$